```
dNdξ[ξ_, η_] := {1/4 (-1 + η), (1 - η)/4, (1 + η)/4, 1/4 (-1 - η)};
dNdη[ξ_, η_] := {1/4 (-1 + ξ), 1/4 (-1 - ξ), (1 + ξ)/4, (1 - ξ)/4};

computeBandJ[defPos_, ξ_, η_] := Module[{X, Y, j11, j12, j21,
    j22, detJ, Jinv11, Jinv12, Jinv21, Jinv22, Jmat, Nmat, Dmat, B},

   X = defPos^T[[1]];
   Y = defPos^T[[2]];

   j11  = X.dNdξ[ξ, η];
   j12  = Y.dNdξ[ξ, η];
   j21  = X.dNdη[ξ, η];
   j22  = Y.dNdη[ξ, η];

   detJ = j11 j22 - j12 j21;


   Jinv11 = j22 / detJ;
   Jinv12  = -j12 / detJ;
   Jinv21 = -j21 / detJ;
   Jinv22  =  j11 / detJ;

   Dmat = {{1.0, 0, 0, 0}, {0, 0, 0, 1.0}, {0, 1.0, 1.0, 0}};

   Jmat  = {{Jinv11, Jinv12, 0, 0},
     {Jinv21, Jinv22, 0, 0}, {0, 0, Jinv11, Jinv12}, {0, 0, Jinv21, Jinv22}};

   Nmat = {Riffle[dNdξ[ξ, η], {0, 0, 0, 0}], Riffle[dNdη[ξ, η], {0, 0, 0, 0}],
     Riffle[{0, 0, 0, 0}, dNdξ[ξ, η]], Riffle[{0, 0, 0, 0}, dNdη[ξ, η]]};

   B = Dmat.Jmat.Nmat;

   Return[{B, detJ}]
  ];


computeStress[σn_, Δd_, B_, Ey_, ν_, Y_] :=
  Module[{Δϵ, Cmat, σtr, Str, S, K, Pnp1, σnp1},

   (*Compute strain increment*)
   Δϵ = B.Flatten[Δd];

   (*Compute an elastic trial stress*)
   Cmat = {{Ey / (1 - ν^2), ν Ey / (1 - ν^2), 0},
     {ν Ey / (1 - ν^2), Ey / (1 - ν^2), 0}, {0, 0, Ey / (2 (1 + ν))}};

   σtr = σn + Cmat.Δϵ;

   (*Compute deviatoric trial stress*)
```

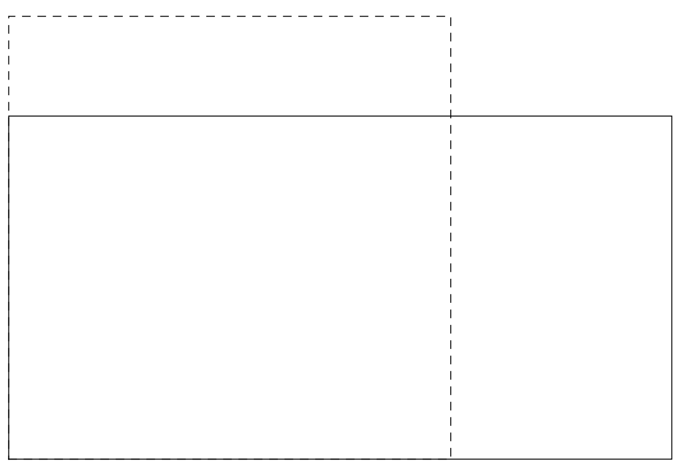
```
Str = σtr - 1/3 (σtr[[1]] + σtr[[2]]) * {1, 1, 0};

(*Compute deviatoric trial stress magnitude*)
S = Sqrt[Str[[1]]^2 + 2 * Str[[3]]^2 + Str[[2]]^2];
(*Check for yielding*)
If[Re[S] ≥ Sqrt[2 / 3.] Y,
 (*yielding, set deviatoric stress to yield stress and add hydrostatic term*)
 σnp1 = Sqrt[2 / 3.] Y * Str / S + 1/3 (σtr[[1]] + σtr[[2]]) * {1, 1, 0};
 ,
 (*not yielding, trial stress is new stress*)
 σnp1 = σtr;
];

Return[{σnp1, Δϵ}]
];


computeForce[defPos_, disp_, Ey_, ν_, Y_, σ1n_, σ2n_, σ3n_, σ4n_] := Module[
  {B1, B2, σ2, B3, B4, J1, J2, J3, J4, σ1np1, σ2np1, σ3np1, σ4np1, Δϵ1, Δϵ2, Δϵ3, Δϵ4},


  {B1, J1} = computeBandJ[defPos, Sqrt[1 / 3.], Sqrt[1 / 3.]];
  {σ1np1, Δϵ1} = computeStress[σ1n, disp, B1, Ey, ν, Y];

  {B2, J2} = computeBandJ[defPos, -Sqrt[1 / 3.], Sqrt[1 / 3.]];
  {σ2np1, Δϵ2} = computeStress[σ2n, disp, B2, Ey, ν, Y];

  {B3,  J3} = computeBandJ[defPos, Sqrt[1 / 3.], -Sqrt[1 / 3.]];
  {σ3np1, Δϵ3} = computeStress[σ3n, disp, B3, Ey, ν, Y];

  {B4, J4} = computeBandJ[defPos, -Sqrt[1 / 3.], -Sqrt[1 / 3.]];
  {σ4np1, Δϵ4} = computeStress[σ4n, disp, B4, Ey, ν, Y];


  Return[{B1ᵀ.σ1np1 J1 + B2ᵀ.σ2np1 J2 + B3ᵀ.σ3np1 J3 + B4ᵀ.σ4np1 J4,
    σ1np1, σ2np1, σ3np1, σ4np1, Δϵ1, Δϵ2, Δϵ3, Δϵ4}]

 ];


computeTangentStiffness[defPos_,
  disp_, Ey_, ν_, Y_, σ1_, σ2_, σ3_, σ4_] := Module[{h, k},

  h = 1 × 10^-50;

  k = Map[computeForce[defPos, Partition[#, 2], Ey, ν, Y, σ1, σ2, σ3, σ4][[1]] &,
    IdentityMatrix[2 Length[nodes]] * I h];

  Return[-Im[kᵀ] / h]
```

```
  ];

(*Setup problem*)
nodes = {{0.0, 0.0}, {1.0, 0.0}, {1.0, 1.0}, {0.0, 1.0}};
disp = ConstantArray[{0.0, 0.0}, Length[nodes]];
defPos = nodes;
Ey = 200;
ν = 0.29;
Y = 15;
σ1n = {0., 0., 0.};
σ2n = {0., 0., 0.};
σ3n = {0., 0., 0.};
σ4n = {0., 0., 0.};
ϵ1 = {0., 0., 0.};
ϵ2 = {0., 0., 0.};
ϵ3 = {0., 0., 0.};
ϵ4 = {0., 0., 0.};

stressStrain = {{{0., 0., 0.}, {0., 0., 0.}}};

(*Begin load stepping iteration*)
Do[

 PrintTemporary["Load Step = ", i];

 (*Apply the initial kinematic BC's*)
 disp = ConstantArray[{0.0, 0.0}, Length[nodes]];
 disp[[2]] += {0.01, 0.0};
 disp[[3]] += {0.01, 0.0};

 (*Begin Newton iteration*)
 Do[

  (*Calculate the total force*)
  {f, σ1np1, σ2np1, σ3np1, σ4np1, Δϵ1, Δϵ2, Δϵ3, Δϵ4} =
   computeForce[defPos, disp, Ey, ν, Y, σ1n, σ2n, σ3n, σ4n];

  (*Zero residual on boundary condition nodes,
  they are are supposed to have reaction forces*)
  f[[{1, 2, 3, 4, 5, 7}]] = {0.0, 0.0, 0.0, 0.0, 0.0, 0.0};

  (*Compute residual*)
  res = Norm[f];

  PrintTemporary["  Residual = ", res];

  (*Break if convergence achieved*)
  If[res < 0.001, Break[]];

  (*Compute tangent stiffness*)
  K = Chop[computeTangentStiffness[defPos, disp, Ey, ν, Y, σ1n, σ2n, σ3n, σ4n]];

  (*Apply essential BC's to tangent stiffness*)
```

```
  K[[1]] = Normal@SparseArray[1 → 1, 2 * Length[nodes]];
  K[[2]] = Normal@SparseArray[2 → 1, 2 * Length[nodes]];
  K[[3]] = Normal@SparseArray[3 → 1, 2 * Length[nodes]];
  K[[4]] = Normal@SparseArray[4 → 1, 2 * Length[nodes]];
  K[[5]] = Normal@SparseArray[5 → 1, 2 * Length[nodes]];
  K[[7]] = Normal@SparseArray[7 → 1, 2 * Length[nodes]];

  (*Solve the linear problem for a displacment increment*)
  disp += Partition[LinearSolve[K, f], 2];

  , {j, 10}
 ];

 (*Update the deformed position and stresses with the converged results*)
 defPos += disp;
 σ1n = σ1np1;
 σ2n = σ2np1;
 σ3n = σ3np1;
 σ4n = σ4np1;
 ϵ1 += Δϵ1;
 ϵ2 += Δϵ2;
 ϵ3 += Δϵ3;
 ϵ4 += Δϵ4;

 AppendTo[stressStrain, {σ3n, ϵ3}]

 , {i, 50}
]

disp = defPos - nodes
```

$\{\{-6.16824\times10^{-18}, 9.94051\times10^{-19}\}, \{0.5, 4.53253\times10^{-18}\}, \{0.5, -0.225196\}, \{0., -0.225196\}\}$

```
Graphics[{{Dashed, Line[{nodes[[1]], nodes[[2]], nodes[[3]], nodes[[4]], nodes[[1]]}]},
  {Line[{defPos[[1]], defPos[[2]], defPos[[3]], defPos[[4]], defPos[[1]]}]}}]
```



```
stress = stressStrain[[All, 1]][[All, 1]];
strain = stressStrain[[All, 2]][[All, 1]];

ListLinePlot[{strain, stress}ᵀ]
```