

## Variational Formulations

Classically "variational formulation" refers to constructing a functional or a variational principle that is equivalent to the governing equation.

The modern use refers to a formulation formulation where the governing eqns are translated into an equivalent weighted-integral statement.

### Weighted Integral Statement

$$u \approx u^h = \sum_{j=1}^n N_j u_j + \sum_{j=1}^m t_j c_j$$

$u_j \rightarrow$  "nodes", but we ~~then~~ have no nodes."

$$u \approx u^h = \sum_{j=1}^m c_j \psi_j + \psi_0 \leftarrow \text{sole purpose is to satisfy the B.C.'s}$$

Consider the O.D.E.

$$-\frac{d}{dx} \left[ a(x) \frac{du}{dx} \right] + c(x) u = f(x) \quad 0 < x < L$$

$$u(0) = u_0, \quad \left[ a(x) \frac{du}{dx} \right]_{x=L} = Q_0$$

$$\text{Let } L = 1, \quad u_0 = 1, \quad Q_0 = 0$$

$$a(x) = x, \quad c(x) = 1, \quad f(x) = 0$$

Let's choose

$$\begin{aligned} \psi_0 &= 1 \\ \psi_1 &= x^2 - 2x \\ \psi_2 &= x^3 - 3x \end{aligned}$$

$$-\frac{d}{dx} \left[ x \frac{du}{dx} \right] + u = 0$$

$$\boxed{\begin{aligned} &= \frac{du}{dx} - x \frac{d^2u}{dx^2} + u = 0 \\ &u(0) = 1, \quad x \frac{du}{dx} \Big|_{x=1} = 0 \end{aligned}}$$

$$u \approx u^h = c_1(x^2 - 2x) + c_2(x^3 - 3x) + 1$$

$$\frac{\partial u}{\partial x} = c_1(2x - 2) + c_2(3x^2 - 3)$$

$$\underline{\frac{d^2 u}{dx^2}} \rightarrow 2c_1 + 6x c_2$$

$$-c_1(2x - 2) - c_2(3x^2 - 3) - 2x c_1 - 6c_2 x^2 + c_1(x^2 - 2x) \\ + c_2(x^3 - 3x) + 1 = 0$$

$$x^3 : \quad c_2 = 0$$

$$x^2 : \quad -3c_2 - 6c_2 + c_1 = -9c_2 + c_1 = 0$$

$$x^1 : \quad -2c_1 - 2c_1 - 2c_1 - 3c_2 = -6c_1 - 3c_2 = 0$$

$$x^0 : \quad 2c_1 + 3c_2 + 1 = 0$$

Go back

$$\int_0^L \underbrace{\delta u}_{w} \left[ \underbrace{-\frac{d}{dx} \left[ x \frac{du}{dx} \right] + u}_{R} \right] dx = \int_0^L \delta u \left[ \overbrace{0}^R \right] dx \stackrel{0}{=} \Rightarrow \int_0^1 w R dx = 0$$

$$R = c_2 x^3 + (c_1 - 9c_2) x^2 + (-6c_1 - 3c_2) x + 2c_1 + 3c_2 + 1$$

$$\text{choose } \delta u_1 = 1, \quad \delta u_2 = x$$

$$0 = \int_0^1 1 \cdot R dx = (1 + 2c_1 + 3c_2) + \frac{1}{2}(-6c_1 - 3c_2) + \frac{1}{3}(c_1 - 9c_2) \\ + \frac{1}{4}c_2$$

$$0 = \int_0^1 x \cdot R dx = (1 + 2c_1 + 3c_2) + \frac{1}{2}(-6c_1 - 3c_2) + \frac{1}{4}(c_1 - 9c_2) + \frac{1}{5}c_2$$

$$c_1 = \frac{222}{23} \quad , \quad c_2 = -\frac{100}{23}$$

Depending on the choice of  $\delta u_i$  we arrive at the different weighted residual methods. If we choose  $\delta u_i$

$$\delta u_i = \psi_i \Rightarrow \text{Galerkin Method}$$

$$\delta u_i \neq \psi_i \Rightarrow \text{Petrov-Galerkin Method}$$

$$\delta u_i = \frac{d}{dx} \left( a(x) \frac{du_i}{dx} \right) \Rightarrow \text{least-squares method}$$

$$\delta u_i = \Delta(x - x_i) \Rightarrow \text{collocation method}$$

where  $\Delta$  is a ~~is~~ Dirac Delta function

$$D = 0 \quad x \neq x_i$$

$$D = 1 \quad x = x_i$$

Only L-S methods result in a symm. coeff matrix

$$\begin{bmatrix} 1/3 & -5/4 \\ -3/4 & -31/20 \end{bmatrix} \begin{Bmatrix} c_1 \\ c_2 \end{Bmatrix} = \begin{Bmatrix} 1 \\ 1/2 \end{Bmatrix} \leftarrow \text{not symm.} \quad \text{← not symm.}$$

### Ritz or Rayleigh-Ritz Method

utilizes a quadratic functional referred to as the "weak form"

### Weak Form

Step 1 Same as W-R

$$-\frac{d}{dx} \left[ a(x) \frac{du}{dx} \right] = f(x) \quad \text{for } 0 < x < L$$

subject to

$$u(0) = u_0$$

"essential"  
"Dirichlet"

$$a \frac{du}{dx} \Big|_{x=L} = Q_L$$

"Natural"  
"Neumann"

$$\int_0^L \delta u \left\{ -\frac{d}{dx} \left[ a(x) \frac{du}{dx} \right] - f(x) \right\} dx = 0$$

Step 2 Integrate by parts

$$0 = \int_0^L \left\{ a(x) \frac{d(\delta u)}{dx} \frac{du}{dx} - \delta u f(x) \right\} dx - \int_0^L \delta u \underbrace{\frac{d}{dx} \left( a(x) \frac{du}{dx} \right)}_{Q_L}$$

Step 3 Impose B.C.'s

$$\boxed{0} = \int_0^L \left\{ a(x) \frac{d(\delta u)}{dx} \frac{du}{dx} - \delta u f(x) \right\} dx - \int_0^L \delta u Q_L$$

Weak Form  $\leftrightarrow$  Variational Form

Bilinear Form

The weak form will contain 2 types of expressions, those involving  $\delta u \rightarrow u$  and those involving only  $\delta u$ .

Group

$$B(\delta u, u) = \int_0^L a(x) \frac{d(\delta u)}{dx} \frac{du}{dx} dx$$

$$I(\delta u) = \int_0^L \delta u f(x) dx + \int_0^L \delta u Q_L$$

$$f(x)$$

We can write: the problem is state as, find  $u$ :

$$B(\delta u, u) = I(\delta u) \quad \text{"variational problem"}$$

The functional  $B(\delta u, u)$  is said to be bilinear

$$B(\alpha u_1 + \beta u_2, v) = \alpha B(u_1, v) + \beta B(u_2, v)$$

$$B(u, \alpha v_1 + \beta v_2) = \alpha B(u, v_1) + \beta B(u, v_2)$$

$B$  is symm.

$$B(u, v) = B(v, u)$$

If bilinear + symm.

$$B(\delta u, u) = \frac{1}{2} \delta B(u, u), \quad I(\delta u) = J(u)$$

$$\frac{1}{2} \delta B(u, u) - \delta J(u) = \delta J(u) = 0$$

Restate the variational problem

$$J(u) = \frac{1}{2} B(u, u) - J(u)$$