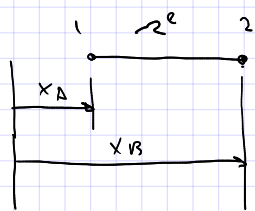


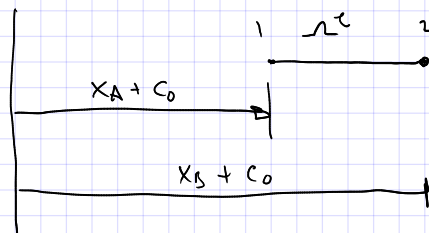
Lagrange polynomial interpolating functions

$$\|u^h - u\|_2$$

$$\sum (u_i^h - u_i)^2$$



deform



$$u_1 = c_0 \quad + \quad u_2 = c_0$$

$$u^h = c_0$$

$$u^h = \sum_j N_j u_j = N_1 u_1 + N_2 u_2 = \frac{N_1 c_0 + N_2 c_0}{c_0} = \frac{c_0}{c_0}$$

Partition-of-unity $\rightarrow N_1 + N_2 = 1$

$$N_i(x_j) = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases} = \delta_{ij} \rightarrow \text{Kronecker Delta Property}$$

$$-\frac{d}{dx} \left(a \frac{du}{dx} \right) + cu - f = 0 \quad \text{for } a < x < b$$

Subject to Neumann B.C.'s

$$\left(a \frac{du}{dx} \right) \Big|_{x=a} = Q_a \quad + \quad \left(a \frac{du}{dx} \right) \Big|_{x=b} = Q_b$$

Weak Form

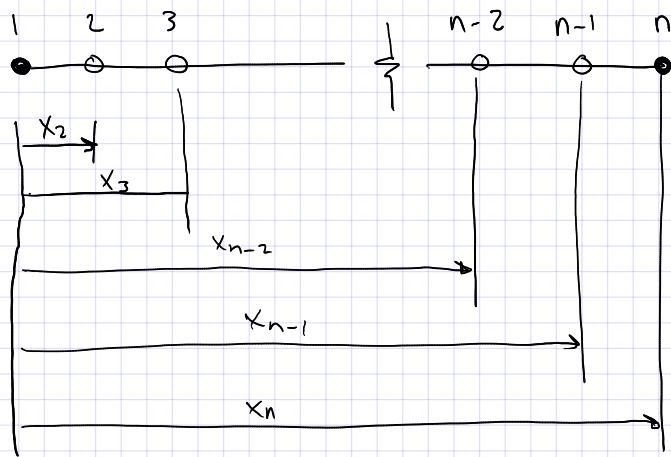
$$\int_a^b \left[a \frac{d(\delta u)}{dx} \frac{du}{dx} + c \delta u u - \delta u f \right] dx - \delta u(a) Q_a - \delta u(b) Q_b$$

$$B(\delta u, u) = \int_a^b \left[a \frac{d(\delta u)}{dx} \frac{du}{dx} + c \delta u u \right] dx$$

$$l(\delta u) = \int_a^b \delta u f dx + \delta u(a) Q_a + \delta u(b) Q_b$$

$$B(\delta u, u) = l(\delta u) \Rightarrow B(N_i, N_j u_j) = l(N_i)$$

$$u \approx u^h = \sum_{j=1}^n N_j u_j \quad \text{where } N_j \text{ of degree } n-1 \text{ + } u_j \text{ are the unknowns}$$



$$\begin{aligned}
 0 &= \sum_{i=1}^{n-1} \left\{ \int_{x_i}^{x_{i+1}} \left[a \frac{d(\delta u)}{dx} \frac{du}{dx} + \delta u u - \delta u f \right] dx - \left[\delta u(x) a \frac{du}{dx} \right]_{x_i}^{x_{i+1}} \right\} \\
 &= \int_{x_1}^{x_n} \left[a \frac{d(\delta u)}{dx} \frac{du}{dx} + c \delta u u - \delta u f \right] dx - \delta u(x_1) \left[-a \frac{du}{dx} \right]_{x_1} - \delta(x_2) \left[a \frac{du}{dx} \right]_{x_2} \\
 &\quad - \delta u(x_2) \left[-a \frac{du}{dx} \right]_{x_2} - \dots - \delta(x_{n-1}) \left[a \frac{du}{dx} \right]_{x_{n-1}} - \delta u(x_n) \left[a \frac{du}{dx} \right]_{x_n} \\
 &= \int_{x_1}^{x_n} \left[a \frac{d(\delta u)}{dx} \frac{du}{dx} + c \delta u u - \delta u f \right] dx - \delta u(x_1) Q_1 - \delta u(x_2) Q_2 - \dots \\
 &\quad - \delta u(x_{n-1}) Q_{n-1} - \delta u(x_n) Q_n
 \end{aligned}$$

where

$$Q_1 = \left[-a \frac{du}{dx} \right]_{x_1}$$

$$Q_2 = \left[\left(a \frac{du}{dx} \right)_{x_2^-} - \left(a \frac{du}{dx} \right)_{x_2^+} \right]$$

...

$$Q_{n-1} = \left[\left(a \frac{du}{dx} \right)_{x_{n-1}^-} - \left(a \frac{du}{dx} \right)_{x_{n-1}^+} \right]$$

$$Q_n = \left[a \frac{du}{dx} \right]_{x_n}$$

} = 0

$$0 = \int_{x_a}^{x_b} \left(a \frac{d(\delta u)}{dx} \frac{du}{dx} + c \delta u u \right) dx - \int_{x_a}^{x_b} \delta u f dx - \sum_{j=1}^n \delta u(x_j) Q_j$$

Let $u = u^h \approx N_j u_j$ + $\delta u = N_i$

For $i=1$

$$0 = \int_{x_a}^{x_b} \left[a \frac{dN_1}{dx} \left(\frac{d}{dx} (N_j u_j) \right) + c N_1 (N_j u_j) \right] dx - \int_{x_a}^{x_b} N_1 f dx - \sum_{j=1}^n N_1(x_j) Q_j$$

$$0 = \int_{x_a}^{x_b} \left[a \frac{dN_n}{dx} \frac{dN_j}{dx} u_j + c N_n N_j u_j \right] dx - \int_{x_a}^{x_b} N_n f dx - \sum_{j=1}^n N_n(x_i) Q_j$$

∴ ith equation

$$0 = \int_{x_a}^{x_b} \left[a \frac{dN_i}{dx} \frac{dN_j}{dx} + c N_i N_j \right] dx u_j - \int_{x_a}^{x_b} N_i f dx - Q_i$$

$$B(N_i, N_j) u_j - \underbrace{f_i}_{F_i} - Q_i = 0$$

$$N_i(x_i) = \delta_{ij}$$

$$K_{ij} u_j = F_i$$

$$\vec{u} = K^{-1} \vec{F}$$

Example

$$\text{Let } (x_a, x_b) = (0, L)$$

$$c = 0$$

$$a = AE$$

$$K_{ij} = \int_0^L \left(EA \frac{dN_i}{dx} \frac{dN_j}{dx} \right) dx$$

$$\begin{bmatrix} \frac{AE}{L} & -\frac{AE}{L} \\ -\frac{AE}{L} & \frac{AE}{L} \end{bmatrix} \begin{Bmatrix} u_1 \\ u_2 \end{Bmatrix} = \begin{Bmatrix} 0 \\ P \end{Bmatrix}$$

$$\frac{AE}{L} u_1 - \frac{AE}{L} u_2 = 0 \Rightarrow u_1 = 0$$

$$-\frac{AE}{L} u_1 + \frac{AE}{L} u_2 = P$$

